The Fundamental Principle of Data Science

Harry Crane

Department of Statistics Rutgers

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Web : www.harrycrane.com Project : researchers.one Contact : @HarryDCrane

Burning Questions

What is Data Science?

What is a Foundation?

What is the purpose of a Foundation?

Acknowledgments

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• H. Crane. (2018). Logic of probability and conjecture.

https://philpapers.org/rec/CRALOP

• H. Crane. (2018). *Probabilistic Foundations of Statistical Network Analysis*. Chapman–Hall.



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Foundations of Probability



Foundations of Probability



"Foundations" of Statistics











The F-word

Data	Method	Inference	Rule	Decision
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- Methods Hypothesis tests, Bayesian methods, confidence distributions, fiducial distributions, machine learning — are **not** Foundations.
- Foundations cannot only be based on statistics and probability.
 - Algorithmic methods (clustering, network science, machine learning) are data science.
 - Inferential Models based on Dempster–Shafer theory not strictly probability but still statistics/data science.
- Foundations of Data Science should handle **all kinds of (complex) data** not just sets, sequences, tables, arrays, etc.

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Role of a Foundation:

- Internal (Logical): Provides a 'standard of coherence' by which to assess methods.
 - Frequentist statistics: ad hoc principles/rules of thumb.
 - Bayesian statistics: coherence/Dutch book argument.
 - Inferential Models (Martin & Liu): 'validity' as standard of rigor.
- External (Scientific): Provides a 'standard of falsification' for inferences.
 - Inferences are meaningful/scientific only if they are falsifiable.
 - Any method for data science should have built-in criteria under which inferences would be falsified.

Data \xrightarrow{Method} Inference \xrightarrow{Rule} Decision

Basic Concepts of Data Science:

Fundamental Principle of Data Science (Crane–Martin): A Method is a protocol which takes any piece of data to an inference about every assertion A.

Method : Data $\rightarrow \forall A$ Inference(A).

Identical data structures should lead to identical inferences:

 $D =_{\text{Data}} D' \implies \forall A \operatorname{Method}_D(A) =_{\operatorname{Inference}(A)} \operatorname{Method}_{D'}(A).$

How to make these principles rigorous?

Simple Example: Hypothesis testing (frequentist)

 $\mathsf{Data} \xrightarrow{\mathsf{Method}} \mathsf{Inference} \xrightarrow{\mathsf{Rule}} \mathsf{Decision}$

If the data provides sufficient evidence in favor of A, then inferences should support A.

Hypothesis testing:

H₀ : null hypothesis

• Method: compute a P-value based on the data D:

 $P = \Pr(D \mid H_0).$

- Interpret ' $P < \alpha$ ' as evidence against H_0 (i.e., reject H_0).
- Inference based on *P*:

$$\mathbf{Method}_{D}(H_0) = \begin{cases} \text{reject } H_0, & P < \alpha, \\ \text{inconclusive, otherwise.} \end{cases}$$

Simple Example: Hypothesis testing (Bayes)

Data $\xrightarrow{\text{Method}}$ Inference $\xrightarrow{\text{Rule}}$ Decision

If the data provides sufficient evidence in favor of *A*, then inferences should support *A*.

Hypothesis testing:

- H_0 : null hypothesis
- H₁ : alternative hypothesis
- Method: compute a Bayes factor based on the data *D*:

$$BF = rac{\Pr(D \mid H_1)}{\Pr(D \mid H_0)}.$$

- Interpret BF as measure of evidence in favor of H₁ over H₀ (denoted as A).
- Inference based on P (from Kass & Raftery, 1995):

(inconclusive,	<i>BF</i> < 3.2,
Mothod (A) -	substantial,	$3.2 \le BF \le 10$,
wethou _D (A) = $\left\{ \right\}$	strong,	10 < <i>BF</i> ≤ 100,
l	decisive,	<i>BF</i> > 100.

Formalization: [Data as	s Structu	ire			
	Data	Method	Inference	Rule	Decision	

 Informal: Data is observable structure, including measurements, relations between measurements (interactions, dependencies), etc.

Formalization: Data as Structure



- Informal: Data is observable structure, including measurements, relations between measurements (interactions, dependencies), etc.
- Formal: Represent Data as a topological space whose points consist of observable information (observable 'data') and the relations between them.



Formalization: The structure of evidence

Data \xrightarrow{Method} Inference \xrightarrow{Rule} Decision	J
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• Informal: Inferences are based on the 'body of evidence' in support of a claim.

Formalization: The structure of evidence

Data \xrightarrow{Method} Inference \xrightarrow{Rule} Decision	
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- Informal: Inferences are based on the 'body of evidence' in support of a claim.
- Formal: Represent the body of evidence for *A* as a **topological space Evid**(*A*) whose points are pieces of evidence in favor of *A* and paths are relations between pieces of evidence.



 $\mathbf{Evid}(A) \equiv \text{Body of evidence supporting } A$

a, a', a'' are distinct pieces of evidence for A

Formalization: The logical structure of inference

Data \xrightarrow{Method} Inference \xrightarrow{Rule} Decision	J
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• Informal: An inference is a judgment about evidential strength (based on data).

Formalization: The logical structure of inference

Data	$a \xrightarrow{Method}$	Inference	$\xrightarrow{\textit{Rule}}$	Decision	

- Informal: An inference is a judgment about evidential strength (based on data).
- Formal: Represent Inference(A) as the disjoint union of spaces whose points are evidence in favor of A, in favor of $\neg A$, or that the outcome is inconclusive.

 $Inference(A) \equiv Evid(A) \cup Evid(\neg A) \cup Inconclusive(A).$

• Can account for strength of evidence (strong, suggestive) but simple case here.



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(1) For any assertion A there is a space of evidence for that assertion:

 $\frac{A \in \textbf{Space}}{\textbf{Evid}(A) \in \textbf{Space}}$

(2) If A has been proven, then there is evidence to support A:

 $\frac{A \in \text{Space}}{a \in A}$ $\frac{a \in A}{\texttt{evid}_A(a) \in \texttt{Evid}(A)}$

(3) If A implies B, then evidence for A implies evidence for B:

 $\begin{array}{c} A \in \textbf{Space} \quad B \in \textbf{Space} \\ f: A \rightarrow B \\ \hline \texttt{imp}(f): \textbf{Evid}(A) \rightarrow \textbf{Evid}(B) \end{array}$

(4) There is no evidence for a contradiction (\emptyset) :

$$\mathsf{Evid}(\emptyset) \equiv \emptyset$$





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 $\frac{A\in \textbf{Space}}{\textbf{Evid}(A)\in \textbf{Space}}\quad (1)$



$$\frac{A \in \text{Space}}{\text{Evid}(A) \in \text{Space}} \quad (1) \qquad \frac{a \in A}{\text{evid}_A(a) \in \text{Evid}(A)} \quad (2)$$





 $Evid(A) \equiv$ Space whose points are evidence supporting A

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The Logic of Evidence: Full Picture (Crane, 2018)



The following can be derived as **theorems** from the rules (1)-(4).

• $\operatorname{Evid}(A \cap B) \to \operatorname{Evid}(A) \cap \operatorname{Evid}(B) \to \operatorname{Evid}(A) \cup \operatorname{Evid}(B) \to \operatorname{Evid}(A \cup B)$

Inferences supporting 'A and B' (jointly) support inferences for A and for B (individually), which in turn supports inferences for A or inferences for B, which supports inference for 'A or B'. (Arrows do not reverse in general.)

Universal/Existential quantification:

• Evid $(\forall a \in A, B(a)) \rightarrow \forall a \in A, Evid(B(a)).$

Inference that B(a) holds for all $a \in A$ supports inference that B(a) holds for every $a \in A$.

•
$$\exists a \in A$$
, $\mathsf{Evid}(B(a)) \to \mathsf{Evid}(\exists a \in A, B(a))$.

Inferring B(a) for some $a \in A$ supports inference that there exists a : A such that B(a) holds.

Derived inference rules:

• $Evid(A) \cap (A \rightarrow B) \rightarrow Evid(A \cap B)$

Inferring A and proving that A implies B supports inference in A and B.

•
$$A \cap \text{Evid}(A \rightarrow B) \rightarrow \text{Evid}(A \cap B)$$
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Formalization in Coq/UniMath: Definition of Evid as a homotopy type

 $A \in \mathbf{Space}$ (1) $Evid(A) \in Space$ $A \in \mathbf{Space}$ *a* ∈ *A* (2) $evid_A(a) \in Evid(A)$ $A \in$ Space $B \in$ Space $f: A \rightarrow B$ $imp(f) : Evid(A) \rightarrow Evid(B)$ (4) $Evid(\emptyset) \equiv \emptyset$

Written in Coq using UniMath library:

(** * Foundations of Data Science Harry Crane Started on May 1, 2018 Preparation for BFF 5 talk at University of Michigan on "The Fundamental Principle of Data Science" Implementation of basic theorems from H. Crane. (2018). Logic of probability and conjecture. https://philpapers.org/rec/CRALOP (** *** Settings *) Unset Automatic Introduction. (* The above line has to be removed for the file to compile with Con8.2 *) (** *** Imports *) Require Export UniMath.Foundations.Preamble. Require Export UniMath.Foundations.PartA. Require Export UniMath.Foundations.UnivalenceAxiom. (* end of "Preamble" *) (* Define Evidence type former *) Definition Space := UU. Inductive Evid (A : Space) : Space := | evid : A → Evid A. (* Elimination, Computation, and Zero rules for Evidence Type *) Hypothesis imp: □ (A : Space) (P : Evid A → Space), $(\Pi a : A, P (evid A a)) \rightarrow \Pi p : Evid A, Evid (P p).$ Hypothesis comp : [] (A : Space) (P : Evid A → Space) (d : ([] a : A, P (evid A a))), ([] a:A, (imp A P d) (evid A a) = evid (P (evid A a)) (d a)). Hypothesis evid zero : Evid @ = @. (* Special case of imp for nondependent types *) Definition Prob imp nondep : [] {A B : Space}, (A \rightarrow B) \rightarrow (Evid A \rightarrow Evid B). Proof. intros A B f a. apply (imp A (λ _, B) (λ a, f a)) in a. apply a. Defined. TU:**- FPDS-BFF5-1 Top L11 (Cog Script(0-) Holes)

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Theorems mentioned earlier:

 $Evid(A \cap B) \rightarrow Evid(A) \cap Evid(B)$

 $Evid(A) \rightarrow Evid(A \cup B)$

 $Evid(B) \rightarrow Evid(A \cup B)$

 $Evid(A) \cup Evid(B) \rightarrow Evid(A \cup B)$

Written in Coq using UniMath library:

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(* Theorems for product and coproduct *)
Theorem split prob: ∏ (A B : Space), Evid ( A × B ) → Evid A × Evid B.
Proof. intros A B. intros x.
       assert (H: Evid (A × B) → Evid A). { intros.
                                              apply (@Prob_imp_nondep (A × B) A pr1) in x. apply x. }
       assert (H': Evid (A × B) → Evid B), {intros, apply (@Prob imp nondep (A × B) B pr2) in x, apply x,
       split.
       - apply H in x. apply x.
       - apply H' in x. apply x.
0ed.
Notation "A II B" := (coprod A B) (at level 20); type scope,
Theorem inl prob : ∏ {A B : Space}, Evid A → Evid ( A ∏ B ),
Proof.
  intros A B. intros x.
  Check Prob_imp_nondep.
  apply (@Prob imp nondep A (A [] B) (@inl A B)) in x.
 apply x.
Qed.
Theorem inr_prob : [] {A B : Space}, Evid B → Evid ( A [] B ).
Proof.
  intros A B. intros x.
  apply (Prob imp nondep (@inr A B)) in x.
  apply x.
Oed.
Theorem prod_co_prob : [] (A B : Space), Evid ( A × B ) → Evid ( A [] B ).
Proof, intros A B, intros x,
       apply (@Prob imp nondep ( A × B ) (coprod A B) (fun y => @inl A B (pr1 y))) in x, apply x,
Qed.
Theorem join_prob : [] (A B : Space), Evid A [[ Evid B → Evid ( A [] B ).
Proof.
  intros A B. intros x.
  destruct x.
  - apply inl prob. apply e.
 - apply inr prob. apply e.
Oed.
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Can these properties be interpreted in a familiar statistics/data science context?

Can interpret the space of evidence in terms of

- Probability functions on fixed set Ω.
- Spaces of probability measures (Giry monad in Category Theory).
- Similarly, finitely additive probabilities as in 1 and 2.
- Dempser–Shafer belief functions with fixed frame of discernment Ω .
- Spaces of Dempster–Shafer functions.

Immediate connections to

- Maximum likelihood estimation
- Hypothesis testing: P-values, Bayes factors
- Inferential Models

There are many ...

- Develop the theory further.
- Shore up the semantics in terms of existing approaches.
- Formalize existing statistics, machine learning, algorithmic approaches in this framework.
- Many more

References

• H. Crane. (2018). Logic of probability and conjecture.

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• H. Crane. (2017). Probability as Shape. Talk at BFF4. Video available at

https://youtu.be/cnDKO0jY6dY

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